$$\Gamma(z) := I_K - \sum_{i=1}^{p-1} \Gamma_i z^i,$$

$$B_*(z) := Q[\Gamma(z)\bar{\beta}(1-z) - \alpha z : \Gamma(z)\beta_{\perp}],$$

$$B(z) = I_K - \sum_{i=1}^p B_i z^i := Q^{-1}B_*(z)Q,$$
(6.3.13)

and

$$\Theta(z) := B(z)^{-1} = \sum_{j=0}^{\infty} \Theta_j z^j.$$

Notice that $B(0) = Q^{-1}B_*(0)Q = [\bar{\beta} : \beta_{\perp}]Q = I_K$. Hence, B(z) has the representation $I_K - \sum_{i=1}^p B_i z^i$ stated in (6.3.13). Moreover, the matrix operator $\Theta(z)$ can be decomposed as

$$\boldsymbol{\Theta}(z) = \boldsymbol{\Theta}(1) + (1-z)\boldsymbol{\Theta}^*(z),$$

where expressions for the Θ_j^* 's can be found by comparing coefficients in $\Theta(z) = \sum_{j=0}^{\infty} \Theta_j z^j$ and

$$\Theta(1) + (1-z)\Theta^{*}(z) = \Theta(1) + \sum_{j=0}^{\infty} \Theta_{j}^{*} z^{j} (1-z)$$
$$= (\Theta(1) + \Theta_{0}^{*}) + \sum_{j=1}^{\infty} (\Theta_{j}^{*} - \Theta_{j-1}^{*}) z^{j}.$$

Hence,

$$\boldsymbol{\Theta}_0 = \boldsymbol{\Theta}(1) + \boldsymbol{\Theta}_0^*$$

and

$$\boldsymbol{\Theta}_i = \boldsymbol{\Theta}_i^* - \boldsymbol{\Theta}_{i-1}^*, \quad i = 1, 2, \dots$$

Using the last expression, we get by successive substitution,

$$\Theta_{i}^{*} = \Theta_{i} + \Theta_{i-1}^{*} = \sum_{j=1}^{i} \Theta_{i-j} + \Theta_{0}^{*}$$
$$= \sum_{j=1}^{i} \Theta_{i-j} + \Theta_{0} - \Theta(1) = -\sum_{j=i+1}^{\infty} \Theta_{j}, \quad i = 1, 2, \dots$$
(6.3.14)

From these quantities the operator $\Xi^*(z)$ in (6.3.11) can be obtained as

$$\boldsymbol{\Xi}^*(z) = [\boldsymbol{\beta}_\perp \boldsymbol{\bar{\beta}}'_\perp \boldsymbol{\Theta}^*(z) + \boldsymbol{\bar{\beta}} \boldsymbol{\beta}' \boldsymbol{B}(z)^{-1}]$$
(6.3.15)

(see the proof of Proposition 6.1). The representation (6.3.11) will turn out to be useful, for example, in Chapter 9, where structural VECMs are discussed. The coefficient matrices Ξ_j^* of the operator $\Xi^*(z)$ will then play an important role as specific impulse response coefficients.